





TRAINING KIT – HAZA01

FLOOD MONITORING WITH SENTINEL-1 USING S-1 TOOLBOX - JANUARY 2015, MALAWI









Research and User Support for Sentinel Core Products

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1 Introduction to RUS

The Research and User Support for Sentinel core products (RUS) service provides a free and open scalable platform in a powerful computing environment, hosting a suite of open source toolboxes pre-installed on virtual machines, to handle and process data derived from the Copernicus Sentinel satellites constellation.



Malawi floods January 2015 Credits: www.theguardian.com [February 10, 2015]

The Republic of Malawi declared a State of Disaster on 13 January 2015 in the 15 affected districts (out of a total of 28 districts). The southern districts of Nsanje, Chikwawa, Phalombe and Zomba were the most affected.

The area experienced heavy rains, more than 150% of normal rainfall, throughout December and January, partially related to Cyclone Bansi and Tropical Storm Chedza, which led to severe flooding. The flood left 276 people dead

and estimated 230 000 displaced with some areas completely inaccessible. It also caused extensive damage to crops, livestock and infrastructure with estimated 64 000 hectares of land damaged, further deepening the humanitarian disaster.

2 Training

Approximate duration of this training session is one hour.

The Training Code for this tutorial is HAZA01. If you wish to practice the exercise described below within the RUS Virtual Environment, register on the <u>RUS portal</u> and open a User Service request from Your RUS service > Your dashboard.

2.1 Data used

 Four Sentinel-1A IW GRDH images with VV polarization acquired before the flood event on 29 December 2014 and during the flood event on 22 January, 27 February and 23 March 2015 [downloadable @ <u>https://scihub.copernicus.eu/</u>]

S1A_IW_GRDH_1SSV_20150323T030724_20150323T030752_005153_0067F3_832F.zip S1A_IW_GRDH_1SSV_20150227T030723_20150227T030752_004803_005F89_DB68.zip S1A_IW_GRDH_1SSV_20150122T030723_20150122T030752_004278_005347_8809.zip S1A_IW_GRDH_1SSV_20141229T030724_20141229T030753_003928_004B86_DA25.zip

 Sentinel-1 Precise Orbits (PODs) for the corresponding dates (auxiliary data) automatically downloaded [downloadable @ <u>https://qc.sentinel1.eo.esa.int</u>]

2.2 Software in RUS environment

Internet browser, SNAP + Sentinel-1 Toolbox, QGIS

3 Register to RUS Copernicus

To repeat the exercise using a RUS Copernicus Virtual Machine (VM), you will first have to register as a RUS user. For that, go to the RUS Copernicus website (<u>www.rus-copernicus.eu</u>) and click on *Login/Register* in the upper right corner.

Research and User Support	NG Star Login / Register 🔒
The RUS Service • The RUS Offer • The RUS Library • The RUS Community •	
	Search
	▼ News from RUS
	One year on!
	Copernicus Info Session – Reykjavik – 19 September 2018
	SPIE Remote Sensing 2018 – Berlin (Germany) – 11-12 September 2018
	SIWI World Water Week 2018 – Stockholm – 26-31 August 2018
	MedRIN Kick-off Meeting – Chania – 13 & 14 July 2018
	RUS Webinar – Special edition "AskRUS – Sentinel-1" – 12 July 2018
 Welcome to Research and User Support 	RUS Training Session - Valencia - 22 July 2018
	IGARSS 2018 - Valencia - 22-27 July 2018
Welcome to the Copernicus Research and User Support (RUS) Service portal!	▼ The RUS agenda
The RUS Service is the "New Expert Service for Sentinel Users" funded by the European Commission,	Conferences & Workshops

Select the option *Register Copernicus SSO account*. A pop-up message will appear informing you that during the second step of the registration process, and when you will be requested to complete your profile in the Copernicus Data Service Portal, you should select **Public** as user category in order to ease and speed up the registration process. Click Ok

Login / Register	WARNING
The registration system to access the RUS service platform has moved toward the COPERNICUS Single Sign On authentication server. New Users who have not yet registered to the RUS portal shall first create a COPERNICUS SSO account. Note that your Copernicus SSO account will be activated only after the reception of the third email sent by the Copernicus service. We advise you to consult this document and this page to facilitate your registration procedure. REGISTER COPERNICUS SSO account can login here: Login	During the second step of the registration process and when you will be requested to complete your profile in the Copernicus Data Service Portal, please select Public as the user category in order to ease and speed up the registration process. Persons willing to use a gmail account for registration shall check their Spam folder regularly. RUS emails tend to be filtered by Google.
Close	ОК

Then, fill in the fields on the Copernicus Users' Single Sign On Registration. Then click Register

CE CSA cds-sso	_	_	-
Copernicus Users'	Single Sign On Re	gistration	
Registration form			
I'm already registered		0	
CDS-SSO ID		0	
Secret question	Select secret question!	v 🕢	
Answer		0	
Password		0	
Confirm password		0	
Email		0	
Confirm email		0	
First name		0	
Last name		0	
Institution		0	
Country of residence		v 🕢	
	dsafn		
Type the characters		0	
	Register		

Once you click on the registration button, you will be requested to complete your profile in the Copernicus Data Service Portal. **WAIT UNTIL YOU ARE REDIRECTED**. This may take up to one minute. Make sure all your User Details are correct, set the company/institution details, select *Public* as user category and click *Submit*.

	user's personal area	European Commission
e		
r Registration Request		
User Details	Account Details	
First Name	Company/Institution *	
Last Name	User Category*	
	Copernicus_Services	
Email	INT_ORG_NGO Public	
	Public_Auth	
Username	Csp Name Csp Role	
Country	· · · · · · · · · · · · · · · · · · ·	T
City		
City		
Postal Code		
Address		
Phone		
Mobile phone		

Your Copernicus SSO account must be validated by an operator. You will then receive an e-mail with activation link. Follow the instructions in the e-mail to activate your account and log-in.

Once you receive the third email, you will be able to Login. You can now return to <u>https://rus-copernicus.eu/</u>, click on Login/Register, choose Login and enter your chosen credentials.

Login / Register	Credentials	
The registration system to access the RUS service platform has moved toward the COPERNICUS Single Sign On authentication server. New Users who have not yet registered to the RUS portal shall first create a COPERNICUS SSO account. Note that your Copernicus SSO account will be activated only after the reception of the third email sent by the Copernicus service. We advise you to consult this document and this page to facilitate your registration procedure. REGISTER COPERNICUS SSO account can login here:	CDS-SSO ID Password Max Idle Time half a day Max Session Time Until browser close Login Reset	0 0 7 0 7 0
Login	Forgot your password?	

4 Request a RUS Copernicus Virtual Machine

Once you are registered as a RUS user, you can request a RUS Virtual Machine to repeat this exercise or work on your own projects using Copernicus data. For that, log in and click on *Your RUS Service -> Your Dashboard.*

CORRESPONDENCE Research and User Support	\$\$ F\$ {	Hello, Miguel
Your RUS service	 Your RUS service Your profile Your dashboard Your training 	You are here: Home > Your RUS service
 Your profile: displays your personal information linked to your ESA SSO and RUS accour Your dashboard: allows you to access your private dashboard, Your training: allows you to register to a training session you have been invited to partic 		News from RUS One year on! Copernicus Info Session - Reykjavik - 19 September 2018 SPIE Remote Sensing 2018 - Berlin (Germany) - 11-12 September 2018 SIWI World Water Week 2018 - Stockholm - 26-31 August 2018 MedRIN Kick-off Meeting - Chania - 13 & 14 July 2018
		RUS Webinar - Special edition "AskRUS - Sentinel-1" - 12 July 2018 RUS Training Session - Valencia - 22 July 2018 IGARSS 2018 - Valencia - 22-27 July 2018

Click on *Request a New User Service* to request your RUS Virtual Machine. Complete the form so that the appropriate cloud environment can be assigned according to your needs.

	Research and User Support	en mes te te	Hello, Miguel
The RUS Service	The RUS Offer 🔻 The RUS Library	▼ The RUS Community ▼ 👷 Your RUS service ▼	
			You are here: Home > Your RUS service > Your dashboard
 Your dashboard 			
Request a new Us	er Service		Chat with Support Desk

If you want to repeat this tutorial (or any previous one) select the one(s) of your interest in the appropriate field.

🔹 User Su	upport Request
	Step 1/3 Your experience
	Please help us learn more about your background by answering a few questions. This information will be stored in your User Profile.
	How many years of experience in Remote Sensing do you have? Choose one item
	Have you already downloaded Copernicus data via the Copernicus Open access hubs?
	Have you already handled/processed Copernicus data?
ſ	Do you wish to practice a tutorial exercise shown in a RUS webinar? If yes, please select your choice (hold down CTRL key for multiple selections).
	HAZA01 - Flood Mapping in Malawi HAZA02 - Burned Area Mapping in Portugal HYDR01 - Vater Bodies Mapping over Northern Poland LAND04 - Crop Mapping in Seville LAND04 - Land Monitoring in Cyprus OCEA01 - Ship Detection in Guilf of Trieste
	If you wish to request another tutorial exercise that doesn't appear in the above list, please type here its name or code. Note that you can request multiple tutorial exercises.
	Cancel Next

Complete the remaining steps, check the terms and conditions of the RUS Service and submit your request once you are finished.

 User Support Request 							
Summary information on your request:							
This is a collection of information selected	s is a collection of information selected across the USR forms.						
You can go back and edit this information	if necessary.						
General information on your request:							
Years of experience in Remote Sensing	5-10 years						
Downloaded Copernicus data?	√						
Handled/processed Copernicus data?	\checkmark						
Webinar codes	HAZA02, LAND04						
About your RUS project:							
Thematic area	Cryosphere (ice and snow)						
Operations to perform on RUS	Algorithm development						
Preference for downloading process	Self-downloading						
Foreseen activities and support needs	Develop a land cover classification						
Project name	RUS_Project1						
Earth Observation Data information: Type of Earth Observation Data:							
Sentinel-1	✓						
	S1 - Product 1						
S1 - Product type	GRD						
S1 - Sensor mode							
S1 - Polarisation							
S1 - Orbit direction	·						
Sentinel-2	X						
Sentinel-3	X						
Other	X						
I don't know	X						
Region of interest: Min Latitude	39,3303						
Max Latitude	40.5877						
Min Longitude	-4.6736						
Max Longitude	-2.7205						
Reference polygons							
Data acquisition date(s):							
Additional data specifications							
I have read and agree to the Terms and Back an							

Further to the acceptance of your request by the RUS Helpdesk, you will receive a notification email with all the details about your Virtual Machine. To access it, go you *Your RUS Service -> Your Dashboard* and click on *Access my Virtual Machine*.

The RUS Service	 The R 	US Offer 🔻 T	he RUS Lib	orary The RUS Co	mmunity 🔻 🎡 Your	r RUS service 🔻			
You are here: Home > Your RUS service > Your dashboard									
 Your dashboard 						n an			
Project Name ID Date of submission Status Actions							Chat with Support Desk		
				Follow my project	Get support	Close my service	Access my Virtual Machine(s)	Access my CPU monitoring dashboard	
RUS_training1	231	2017-08-31	Open		Get a webinar kit	Rate my service	Freeze my Virtual Machine(s)	Report a technical incident	

Fill in the login credentials that have been provided to you by the RUS Helpdesk via email to access your RUS Copernicus Virtual Machine.

← → C ▲ Not secure https://usr-231	us-copernicus.eu/#/	:
	EXAMPLE EQUACAMOLE Username Password Login	0.9.14
🦉 Applications		
Bill of typicana Exclose Stansov Deconstantial Stansov Deconstantial Stansov Trackin		

5 Step by step

5.1 Data download – ESA SciHUB

In this step, we will download Sentinel-1 scenes from the Copernicus Open Access Hub using the online interface (**Applications -> Network -> Web Browser** or click the link below).

Go to https://scihub.copernicus.eu/



Go to Open HUB, if you do not have an account please register by going to "sign-up" in the LOGIN menu in the upper right corner.



After you've filled in the registration form, you will receive an activation link by e-mail. Once your account is activated or if you already have an account, log in.

Then click on the map and Navigate to the approximate location of south Malawi. Switch to drawing mode (green arrow) and draw search rectangle approximately as indicated below.



Open the search menu by clicking to the left part of the search bar and specify the following parameters:

Sensing period: From 2014/12/29 to 2015/03/23

Check Mission: Sentinel-1

Product Type: GRD (Ground-range-detected product)

Relative Orbit number: 6 (to ensure identical acquisition geometry for all scenes)



In our case, the search returns only 11 results but this will depend on the exact search area defined. Download the following scenes:

S1A_IW_GRDH_1SSV_20150323T030724_20150323T030752_005153_0067F3_832F S1A_IW_GRDH_1SSV_20150227T030723_20150227T030752_004803_005F89_DB68 S1A_IW_GRDH_1SSV_20150122T030723_20150122T030752_004278_005347_8809 S1A_IW_GRDH_1SSV_20141229T030724_20141229T030753_003928_004B86_DA25

Note that you can only download 2 scenes in parallel. To see the full name of the scene you can click the full screen view (indicated by blue circle below).

You can find instruction how to download larger numbers of products in the Copernicus Open Access Hub User Guide (<u>https://scihub.copernicus.eu/userguide/GraphicalUserInterface</u>)



Move the downloaded scenes (desktop, /home/rus/Downloads) to: /shared/Training/HAZA01_FloodMapping_Malawi_TutorialKit/Original

5.2 SNAP - open and explore data

In *Applications* -> *Other* open **SNAP Desktop**; click Open product // navigate to /*shared/Training/HAZA01_FloodMapping_Malawi_TutorialKit/Original* and open all the downloaded files.

The opened products will appear in Product Explorer. Click + to expand the contents of the file from December 2014, then expand Bands and double click **Amplitude_VV** to visualize the band. Then do the same for the image from 22 January 2015. To compare both images, go to **Window ->Tile Horizontally** and zoom-in to the lower left corner of the image.



5.3 Pre-processing

We need to apply identical pre-processing steps to all our scenes. However, processing the data step by step and product by product would be time consuming and inconvenient. Luckily we can use the **Batch Processing** tool available in SNAP to apply all steps to both images in one go (this also saves disk space as only the final products are physically saved).

5.3.1 Build the Graph

To use the tool, we first need to define the process we want to apply and all its steps. We can do this using the **GraphBuilder**. To build our graph, go to **Tools -> GraphBuilder**.



At the moment, the graph only has two operators: **Read** (to read the input) and **Write** (to write the output).

Since our Area of Interest (AOI) is quite small and there is no need to process the whole image, we start by adding a **Subset** operator. To add the operator right-click the white space in the graph builder and go to **Add -> Raster -> Geometric -> Subset**.

A new operator rectangle appears in our graph and a new tab appears below. Now connect the new **Subset** operator to the **Read** operator by clicking to the right side of the **Read** operator and dragging the red arrow towards the **Subset**.



In the next step, we will update the orbit metadata (See NOTE 1). To add the operator, right-click the white space between existing operators and go to Add -> Radar -> Apply-Orbit-File. Connect the new Apply-Orbit-File operator with the Subset operator.

NOTE 1: The orbit state vectors provided in the metadata of a SAR product are generally not accurate and can be refined with the precise orbit files which are available days-to-weeks after the generation of the product. The orbit file provides accurate satellite position and velocity information. Based on this information, the orbit state vectors in the abstract metadata of the product are updated. (*SNAP Help*)

Read Subset Apply-Orbit-Fil	Write
-----------------------------	-------

The next step will remove the thermal noise (See NOTE 2). We do this by right-clicking the white space somewhere left of the resample operator and going to Add -> Radar -> Radiometric -> ThermalNoiseRemoval. Connect the ThermalNoiseRemoval operator with the Apply-Orbit-File operator.

NOTE 2: Thermal noise in SAR imagery is the background energy that is generated by the receiver itself. (SNAP Help) It skews the radar reflectivity to towards higher values and hampers the precision of radar reflectivity estimates. Level-1 products provide a noise LUT for each measurement dataset, provided in linear power, which can be used to remove the noise from the product.

Now, we can add the **Calibration** operator. The objective of SAR calibration is to provide imagery in which the pixel values can be directly related to the radar backscatter. Though uncalibrated SAR imagery is sufficient for qualitative use, calibrated SAR images are essential to quantitative use of SAR data (See NOTE 3). To add the operator go to Add -> Radar -> Radiometric -> Calibration. Connect the **ThermalNoiseRemoval** operator to the **Calibration** operator.

NOTE 3: Typical SAR data processing, which produces level-1 images, does not include radiometric corrections and significant radiometric bias remains. The radiometric correction is necessary for the pixel values to truly represent the radar backscatter of the reflecting surface and therefore for comparison of SAR images acquired with different sensors, or acquired from the same sensor but at different times, in different modes, or processed by different processors. (*SNAP Help*)



SAR images have inherent salt and pepper like texturing called speckles which degrade the quality of the image and make interpretation of features more difficult (See ANOTE 4). To reduce the speckle effect and smooth the image we apply speckle filter. To add the operator, go to **Radar -> Speckle Filtering -> Speckle-Filter** then connect the **Calibration** operator to it.

NOTE 4: Speckle is caused by random constructive and destructive interference of the de-phased but coherent return waves scattered by the elementary scatters within each resolution cell. Speckle noise reduction can be applied either by spatial filtering or multilook processing. (*SNAP Help*)

Our data are still in radar geometry, moreover due to topographical variations of a scene and the tilt of the satellite sensor, the distances can be distorted in the SAR images. Therefore as the last step of our preprocessing, we will apply terrain correction to compensate for the distortions and reproject the scene to geographic projection (See INOTE 5). To add the operator, go to **Radar -> Geometric -** > **Terrain Correction -> Terrain-Correction** then connect the **Speckle-Filter** operator to it. Finally. Attach the **Terrain Correction** operator to the **Write** operator.

NOTE 5: The geometry of topographical distortions in SAR imagery is shown on the right. Here we can see that point B with elevation h above the ellipsoid is imaged at position B' in SAR image, though its real position is B". The offset Δr between B' and B" exhibits the effect of topographic distortions. (SNAP Help)



Road Subset Apply Orbi	File ThermalNoiceRemoval Calibration	Speckle-Filter
Keau Jubset Apply-Olbi		Speckee neer renameconection white

At the moment, do not change anything in the parameter tabs and save the graph as *Graph_preprocess.xml* to */shared/Training/HAZA01_FloodMapping_Malawi_TutorialKit/Processing* by clicking **Save** at the bottom of the window.

5.3.2 Batch processing

In the **Product Explorer**, we select (highlight) the product [1] (29 December 2014). Now we can close the **GraphBuilder** window and open the **Batch Processing** tool (**Tools -> Batch Processing**).

We will add the opened products by clicking **Add Opened** on the upper right (second icon from the top) and click refresh. Then we click **Load Graph** at the bottom of the window and navigate to our saved graph and open it. We see that new tabs have appeared at the top of window corresponding to our operators with the exception of **Write**; this is correct as these parameters will be set in the **I/O Parameters** tab.

In the I/O Parameters tab set directory to:

/shared/Training/HAZA01_FloodMapping_Malawi_TutorialKit/Processing and make sure the 'Keep source product name' option is selected (See 📜 NOTE 6).

NOTE 6: The product file names will be identical to the input file names. If you set your output directory to the folder that contains your input data the input data will be overwritten.

SNAP	Bato	h Processing	ı : Graph_prep	rocess.xml		↑ □ ×		
F	ile Graphs							
	Calibration Terrain-Co I/O Parameters	orrection Spe Subset	eckle-Filter Apply-Orbit-Fil	e TI	hermalNoiseRe	moval		
	File Name	Туре	Acquisition	Track	Orbit	4		
	S1A_IW_GRDH_1SSV_20	GRD	29Dec2014	6	3928		Add	onened
	S1A_IW_GRDH_1SSV_20	GRD	22Jan2015	6	4278			opened
	S1A_IW_GRDH_1SSV_20		27Feb2015	6	4803			
	S1A_IW_GRDH_1SSV_20	GRD	23Mar2015	6	5153			
						4 Products	Refr	esh
	Target Folder Save as: BEAM-DIMAP	-						
	Directory:							
	/home/rus/shared/Training/HAZA01_FloodMapping_Malawi_TutorialKit/Processing							
	Skip existing target f	iles 🖌 Keep so	ource product nar	ne				
		C		Graph Ri	un <u>C</u> lose	<u>H</u> elp		

Now let's set the parameters. In the Subset tab set the extent of the AOI in pixel coordinates to:

	Batch Processing	: Graph_preprocess.	xml	+ • ×
File Graphs				
ThermalNoiseRemo		Terrain-Correction Sp Subset	eckle-Filter Apply-Orbit-File	
Source Bands:	Amplitude_VV Intensity_VV			
🖌 Copy Metadata				
Pixel Coordinates	🔾 🔾 Geographic Coo	rdinates		
X:	20000	Y:	15500	
Width:	5100	height:	4000	
Sub-sampling X:	1	Sub-sampling Y:	1	
		Load Graph	Run <u>C</u> lose	<u>H</u> elp

X: 20000 Y: 15500 Width: 5100 Height: 4000

In **Apply-Orbit-File** tab we can accept the default settings. In the **ThermalNoiseRemoval** tab select VV polarization and make sure that "Remove Thermal Noise" option is selected.

SNAP	Batch Processing : Graph_preprocess.xml	Ŷ	×
File Graphs			
Calibration Speckle I/O Parameters	e-Filter Terrain-Correction Subset Apply-Orbit-File ThermalNoiseRemo	oval]
Orbit State Vectors: Se	entinel Precise (Auto Download)		-
Polynomial Degree: 3			
	Do not fail if new orbit file is not found		

In the **Calibration** tab, we will also accept all default settings.

SNAP	Batch Processing : Graph_preprocess.xml	¢	×
I	File Graphs		
	Calibration Speckle-Filter Terrain-Correction		 _
1	//O Parameters / Subset / Apply-Orbit-File / ThermalNoiseRemo	val	
	Polarisations: VV		
	Save as complex output		
	🗹 Output sigma0 band		
	Output gamma0 band		
	Output beta0 band		

In the Terrain-Correction tab, set:

Map Projection -> Projection : UTM / WGS84 (Automatic)

Leave all the other default settings.

Batch Process	ing : Graph_preprocess.xml 🔹 🗠 🗙	🛓 Map Projection 🔹 🗉
File Graphs		Coordinate Reference System (CRS)
Calibration Speckle-Filter Terrain	-Correction	Custom CRS
I/O Parameters Subset	Apply-Orbit-File ThermalNoiseRemoval	
Source Bands:	Sigma0 W	Geodetic datum: World Geodetic System 1984 🔻
		Projection: UTM / WGS 84 (Automatic) 💌
		Projection Parameters
		Predefined CRS Select
		<u>O</u> K <u>C</u> ancel <u>H</u> elp
Digital Elevation Model:	SRTM 3Sec (Auto Download)	
DEM Resampling Method:	BILINEAR_INTERPOLATION	
Image Resampling Method:	BILINEAR_INTERPOLATION	
	10.0(m) × 10.0(m)	
Pixel Spacing (m):	10.0	
Pixel Spacing (deg):	8.983152841195215E-5	
Map Projection:	UTM Zone 36, South / World Geodetic System 1984	
🖌 Mask out areas without elevation	Output complex data	
Output bands for:		
Selected source band	DEM Latitude & Longitude	
Incidence angle from ellipsoid	Local incidence angle 🗌 Projected local incidence angle	
Apply radiometric normalization		
Save Sigma0 band	Use projected local incidence angle from DEM	
Save Gamma0 band	Use projected local incidence angle from DEM	
Save Beta0 band		
Auxiliary File (ASAR only):	Latest Auxiliary File 💌	
r	Load Graph Run <u>C</u> lose <u>H</u> elp	

Last we go to the **Speckle-Filter** tab. For this exercise we choose the simple Lee filter with window size of 7x7 pixels (See $\boxed{}$ NOTE 7).

SMAR	Batch Proce	ssing : Graph_preprocess.xml	×
	File Graphs		
	Calibration Speckle-Filter Terr I/O Parameters Subset		
	Source Bands:	Sigma0_W	
	Filter:	Lee	-
	Filter Size X (odd number):	3	
	Filter Size Y (odd number):	3	
	Estimate Equivalent Number of Looks	V	
	Number of Looks:	1.0	
		Load Graph Run <u>C</u> lose <u>H</u> e	lp

NOTE 7: Lee Filter, introduced by Jong-Sen Lee in 1980, is a widely used local statistics filter for speckle noise reduction. It is a pointwise linear filter minimizing the mean square error using measurements of the sample mean and sample variance of the noisy image and knowledge of the type of detection and number of looks.

Then finally click Run to pre-process our images. Approximate processing time: 5 minutes

Now you should have four new products in the **Product Explorer**. Select the original products [1-4], right-click and click **Close 4 Products** (Click No if asked to save).

5.4 Binarization

To separate water from non-water a threshold can be selected for each image. For this, we will analyze the histogram of the filtered backscatter coefficient. Low values of the backscatter will correspond to the water, and high values will correspond to the non-water class.

First, open all four created products [5-8] in the View and then go to **Window -> Tile Evenly**. Click on the view [5]Sigma0_VV to activate it (yellow boundary). On the left side panel select the **Color Manipulation** tab and click A (Stretch the histogram horizontally) on the left side of the tab. Then move the middle slider below on the histogram to approx. ~0.025 and click on $\textcircled{log_{10}}$. Now we can see the water bodies better. Let's apply the same histogram stretch to other three images. To do this click on \fbox{M} and select all three bands and click OK. In next dialog click No (for each band).



To create a binary mask of water and non-water pixels we create a new band and apply a conditional expression based on our threshold. To obtain our threshold value we will check the values occurring over the open water. **Go to Window -> Tile Single**. Go to View [5] Sigma0_VV_db.

You can create your own water body mask, but for this tutorial we will use one that has been prepared in advance and saved in the Auxdata folder. We can import it by clicking on the Product [5] in **Product Explorer** and then going to **Vector** -> **Import** -> **ESRI Shapefile.** Navigate to /shared/Training/HAZA01_FloodMapping_Malawi_TutorialKit/Auxdata and open the shapefile

Water_ROI_Polygon.shp. Click *No* in the **Import Geometry** dialog (import all features into single mask).





Now let's have look at the statistics. In the product explorer, expand the bands folder in product [5] and click on band *Sigma0_VV_db* so it is highlighted. Then go to **Analysis -> Statistics.** A new window will appear. On the right side select \checkmark **Use ROI Mask(s**), select the *Water_ROI_Polygon* (See $\stackrel{\circ}{=}$ TIP 1) and click $\stackrel{\frown}{=}$ **Refresh**.

TIP 1: If the ROI/geometry does not appear in the window go to **Product Explorer**, expand the *Vector Data* folder in product [5] and click on *Water_ROI_Polygon*. Now it should appear in the statistics window as well and you can select it.



Now we can investigate the statistics. We can see that the maximum value in our Water polygons is 0.0236, the statistics also produces 90% percentile which gives a value of 0.0117. For our purposes we will adopt a value close to the 99% percentile which is not provided but can be estimated from the histograms. Let's choose 0.020 as our threshold (the statistics is of course always dependent on the ROI you choose and therefore can vary significantly).

Now let's apply the threshold. We will apply the same threshold to all our images, therefore we can use the Batch processing again.

Firstly, let's build a very simple graph. Go to **Tools -> Graph Builder**, add Band Math operator (rightclick on the white space and go to **Raster -> BandMaths**) and connect the operators as shown below. At the bottom of the window **Save** the graph to the *Processing* folder as *Graph_binary.xml*. Close the **Graph Builder**.



Then go to **Tools -> Batch Processing** and click **Add Opened** on the upper right (second icon from the top) and click refresh. Click on the **Load Graph** button, navigate to our saved graph and open it. We can now see that the **BandMaths** tab has appeared at the top of window.

Make sure that the format is set to **GeoTIFF** in the **I/O Parameters** tab, the directory to /shared/Training/HAZA01_FloodMapping_Malawi_TutorialKit/Processing/Binary and the **Keep** source product name option is selected (See NOTE 6 - Page 8).

Batc	h Processi	ng : Graph_	bin.xml		+ = ×
File Graphs					
I/O Parameters Ba	ndMaths				
File Name	Туре	Acquisition	Track	Orbit	
S1A_IW_GRDH_1SSV	GRD	29Dec2014	6	3928	
S1A_IW_GRDH_1SSV	GRD	22Jan2015	6	4278	
S1A_IW_GRDH_1SSV	GRD	27Feb2015	6	4803	
S1A_IW_GRDH_1SSV	GRD	23Mar2015	6	5153	
Target Folder					4 Products
-		_			
Save as: GeoTIFF	`				
Directory:					
/shared/Training/HAZ					/Bin
		Load Graph	Run	<u>C</u> lose	Help

In the **BandMaths** tab rename the new band to *Water_mask,* open the **Edit Expression...** and enter following expression:

If Sigma0 VV < 0.02 AND Sigma0 VV > 0 then 1 else NaN

If no errors are found close Expression editor by clicking OK and Run the process.

Batch Processing : Graph_bin.xml + 🗆 🗙	Arithmetic Expression Editor 🔹 🔹 🗙
File Graphs I/O Parameters BandMaths Target Band: Water_mask Target Band Type: float32 Band Unit:	Data sources: Expression: Sigma0_VV @ + @ If Sigma0_VV < 0.02 AND Sigma0_VV > 0 Water_ROI_Polygon @ - @ then 1 else NaN @ * @ @ / @ (@)
Expression: Edit Expression Load Graph Run <u>C</u> lose <u>H</u> elp	Constants Show bands Show masks Show tie-point grids Show single flags Operators Constants Operators Constants Derators Constants Co

Four new products [9-12] have appeared in the **Product Explorer**. Close all opened view windows and open the Water_mask band for all the new products. Use **Window -> Tile Evenly** to see all products at the same time.





5.5 Visualization (QGIS)

To better visualize the output of our multi-temporal flood analysis, we will open the saved masks (GeoTIFF) in QGIS. Go to *Application -> Processing -> QGIS Desktop*. Click on the **Add Raster Layer** button located in the left panel (\mathbb{R}), navigate to:

/shared/Training/HAZA01_FloodMapping_Malawi_TutorialKit/Processing select the four water masks and click **Open**.



You can change the style of the layers on the properties menu. Right click on the product you want to change and select **Properties**. In the **Style** tab, select **Multiband color** as rendering type. In the **Color Rendering** section, activate the **Colorize** option, select a color and click OK.

<u>%</u>		Layer Properties - Water_mask_January Style 🔶 🗧 😒
💋 🔀 General	▼ Band rend	aring
💐 Style	Render type	Multiband color
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💼 Pyramids		Min 0 Max 0
📉 Histogram	Green band	Band 2 (Green)
Metadata		Min Max
	Blue band	Band 3 (slue)
E Legend	Contrast enhancement	Min Max No enhancement
	▶ Load min	nax values
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	Hue	Z Colorize Strength]100%]100%]
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	Style •	Thumbnail Legend Palette

Finally, we can add a base-map to link our water masks to GIS data. Click on Web -> OpenLayers plugin -> OpenStreetMap -> OpenStreetMap (See 🗀 NOTE 8).

NOTE 8: In case the **OpenLayers** plugin is not installed, click on **Plugins -> Manage and Install Plugins.** Select the '*All*' tab on the right side panel and write "OpenLayers plugin" on the search box. Select the plugin on the list and click 'Install Plugin'. Restart QGIS to finalize the installation.





THANK YOU FOR FOLLOWING THE EXERCISE!

6 Further reading and resources

Irimescu, A., Gh Stancalie, V. Craciunescu, C. Flueraru, and E. Anderson. "The Use of Remote Sensing and Gis Techniques in Flood Monitoring and Damage Assessment: A Study Case in Romania." In *Threats to Global Water Security*, 167–77. NATO Science for Peace and Security Series C: Environmental Security. Springer, Dordrecht, 2009. doi:10.1007/978-90-481-2344-5_18.

Fayne, J., Bolten, J., Lakshmi, V., & Ahamed, A. (2017). Optical and Physical Methods for Mapping Flooding with Satellite Imagery. In *Remote Sensing of Hydrological Extremes* (pp. 83–103). Springer, Cham. https://doi.org/10.1007/978-3-319-43744-6_5

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